

Rapid multi-physics approach to the development of electric drive systems for hybrid and electric vehicles

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Advanced Technology Group
Electric Power Systems**

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Automotive and Engine Technology**

Presentation Outline

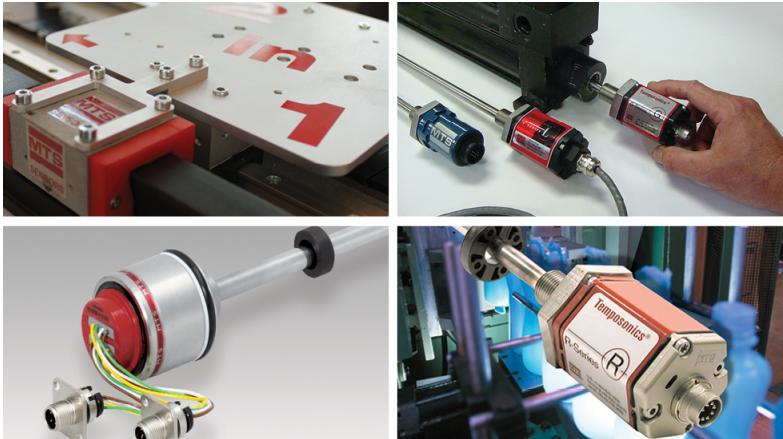
- MTS Systems Corporation
- Electric Power Systems
- Development Cycle for Motors and Drive
- Applications

MTS Products, Systems and Services

Test Vehicles, Materials and Structures



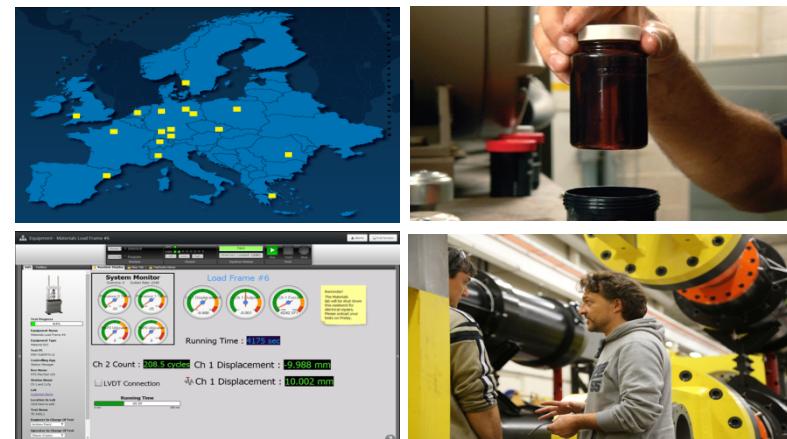
Sensors Liquid level and position



Electric Power Systems Vehicles, Industrial



Services Consulting, Monitoring, Repair



EPS – Electric Power Systems

Develop and manufacture high performance electric motors and controls.

PORTFOLIO

- » Traction motors
- » ERS
- » Dynos
- » Industrial solutions
- » Power generation
- » Oil and gas exploration
- » Aerospace applications

Formula E drive System



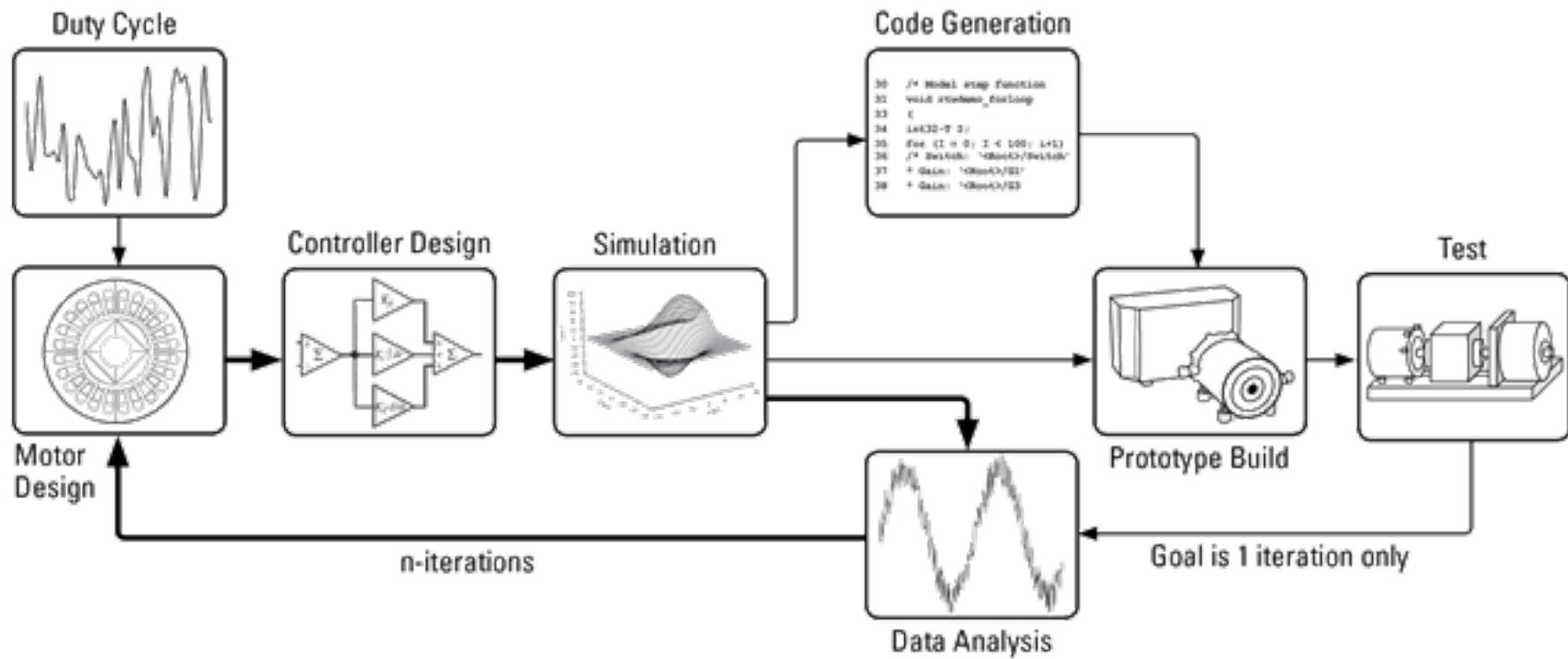
- » Traction drive
- » Kinetic energy recovery

Formula 1 Energy Recovery System

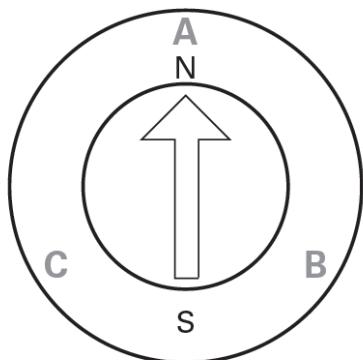


- » Kinetic energy recovery
- » Heat energy recovery

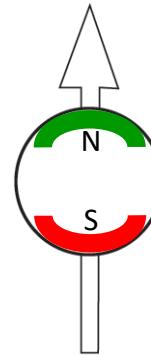
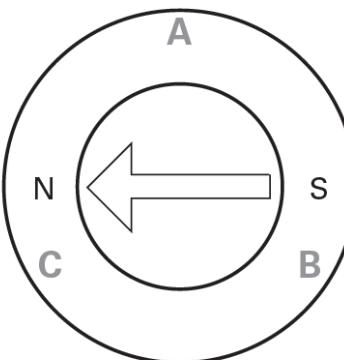
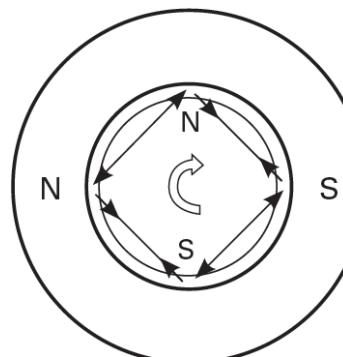
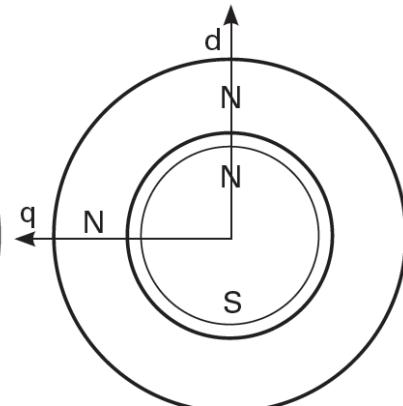
Development Cycle for Motors and Drives



Motor Principle

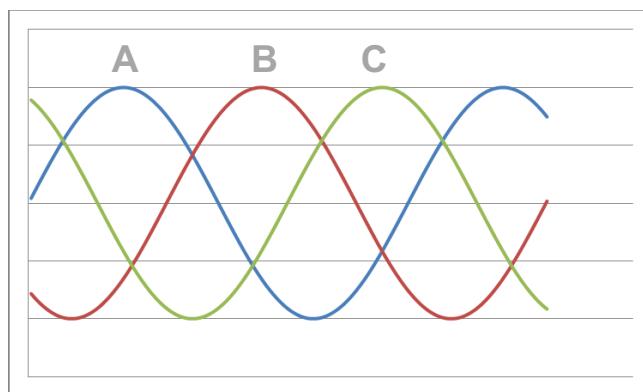


Stator

Rotor
SPMTorque
Rotation

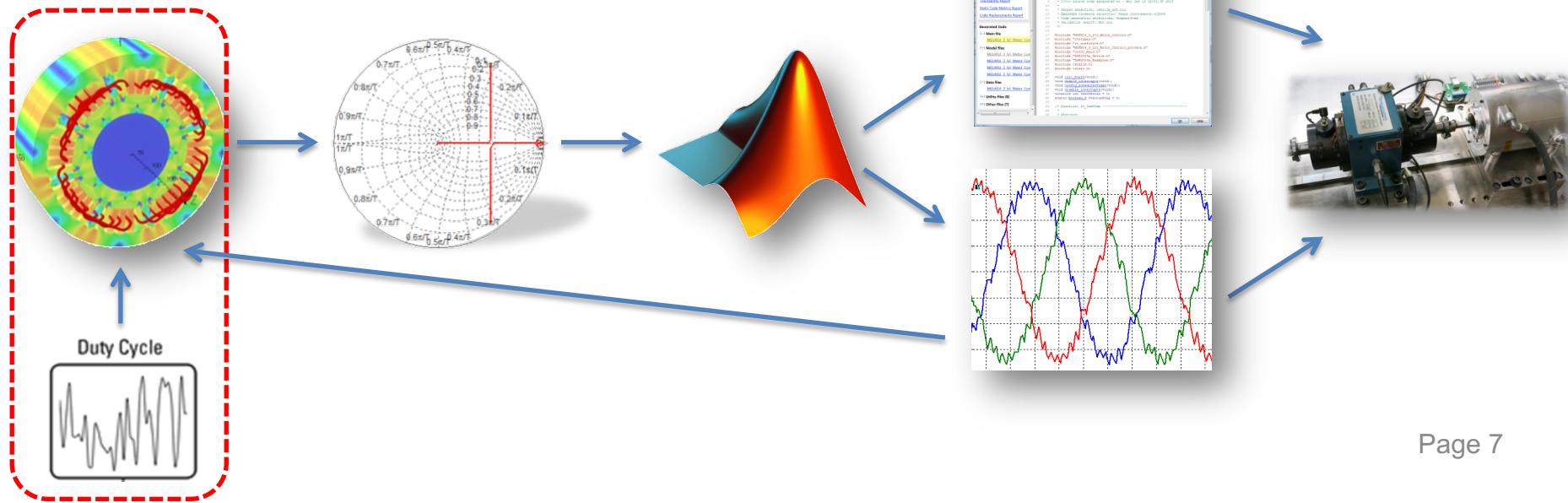
Control

I_q =torque
 I_d ="correction"



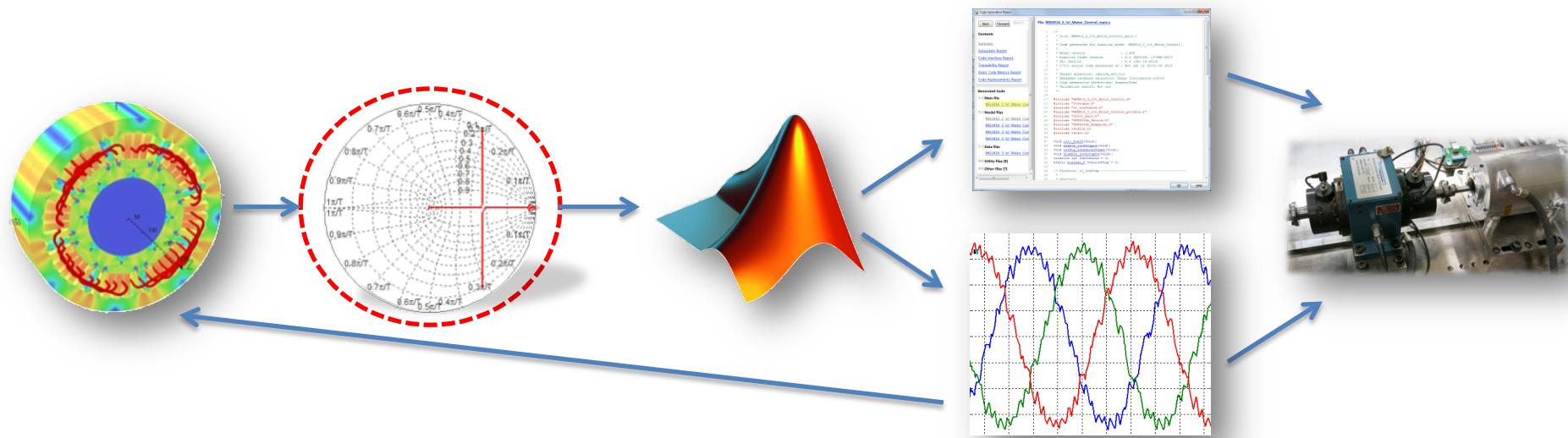
Motor/Drive System Design Process

- Duty Cycle drives base design, topology, etc.
- FEA of EM design
- Control Design
- Simulation
- Data Analysis/Hardware Design
- Code Generation
- Testing & Verification



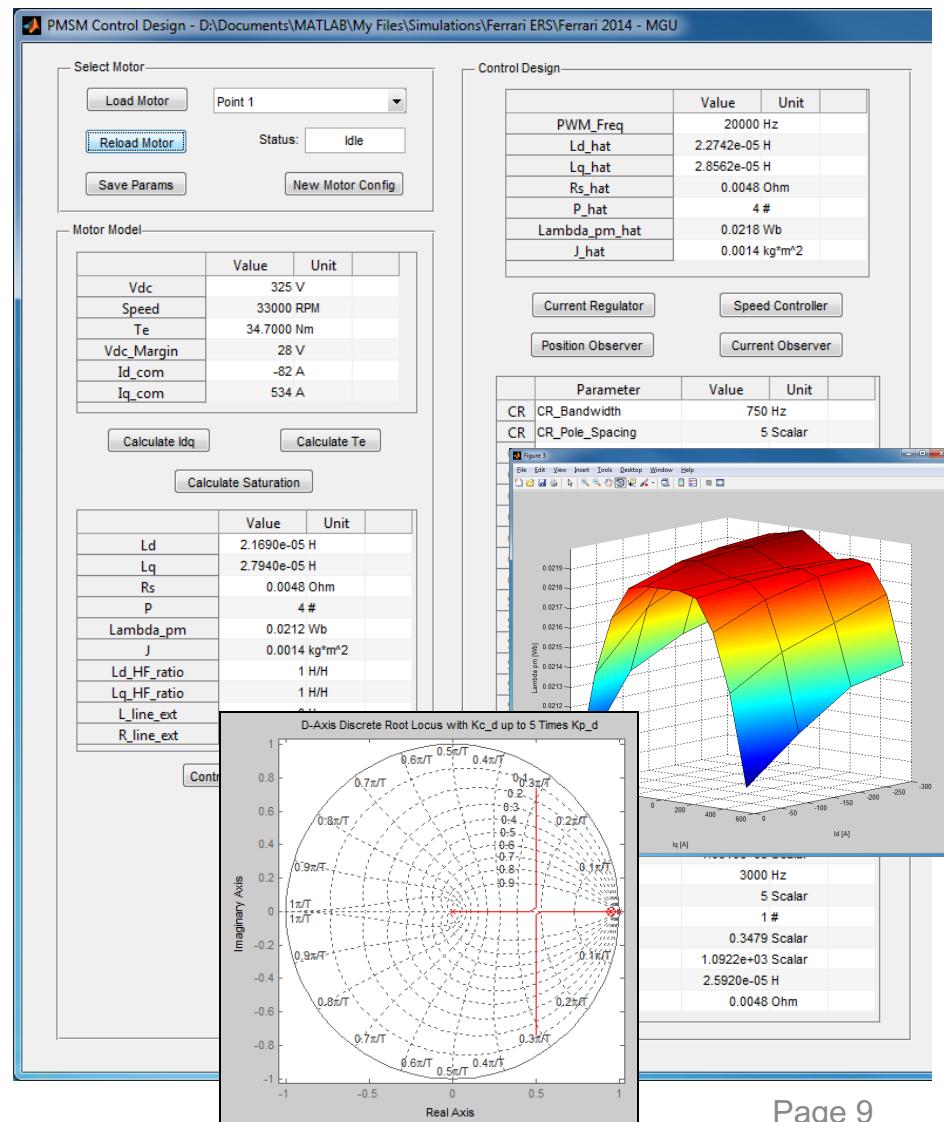
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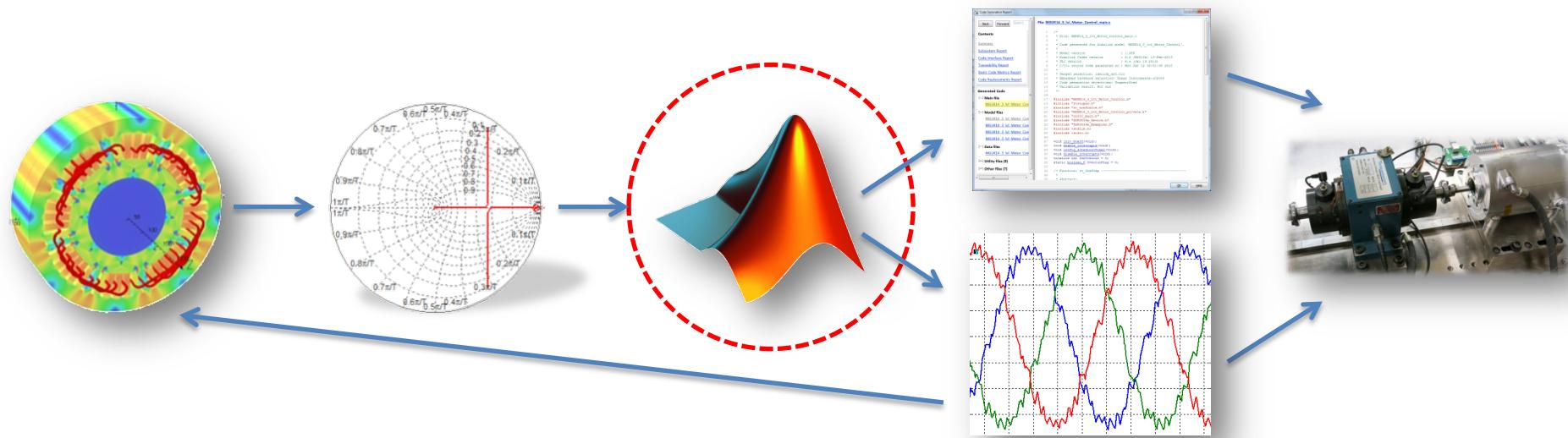
Control Design

- Motor parameters lookup table
 - Generated with FEA
 - L_d , L_q , and Λ vs I_d and I_q
- Discrete control design
 - d-q current commands
 - Speed command
 - Speed observer
 - Current observer (Self Sensing)
- Operating point calculations
 - Including saturation
 - MTPA and Field Weakening
- Rapid and robust control design



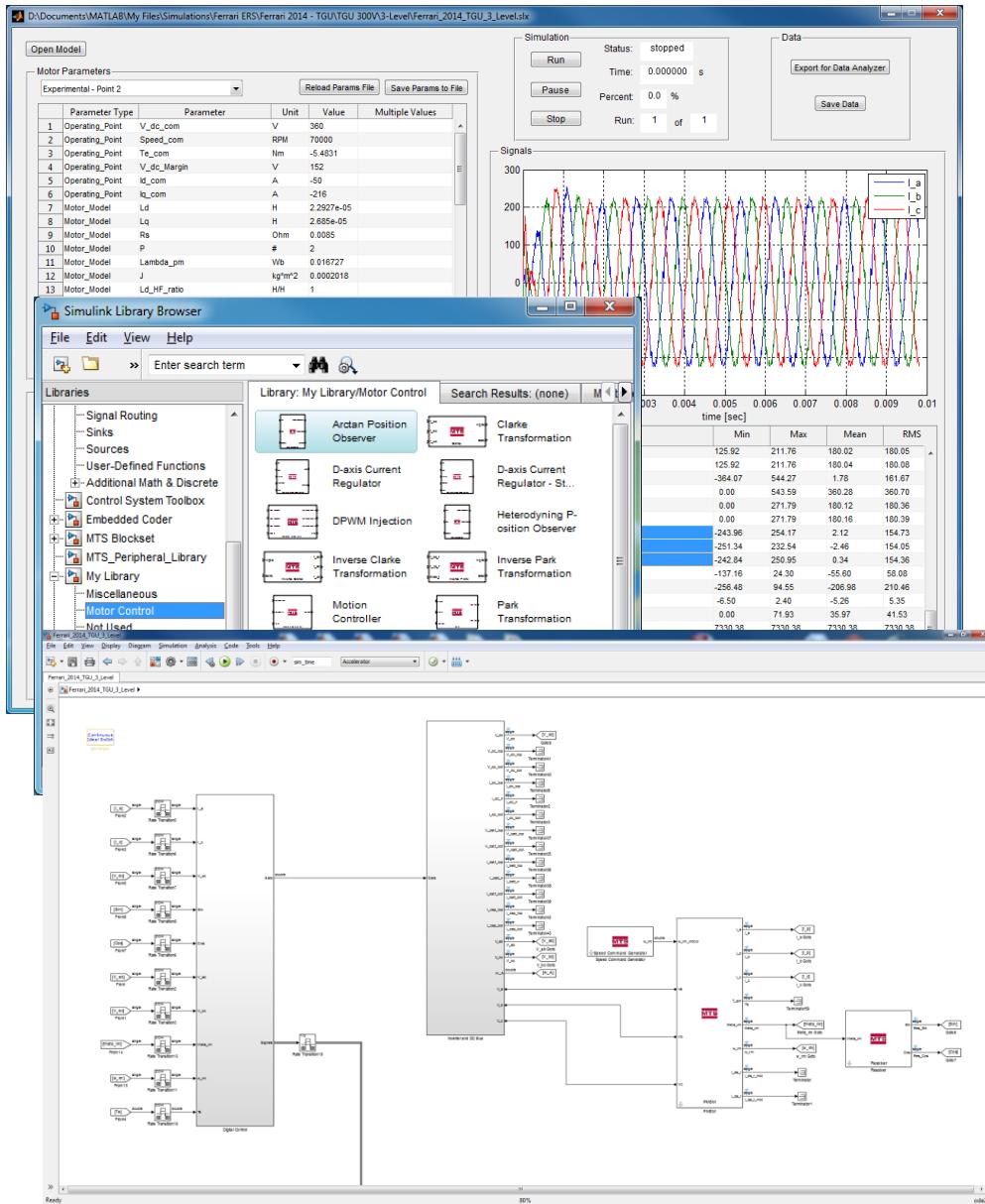
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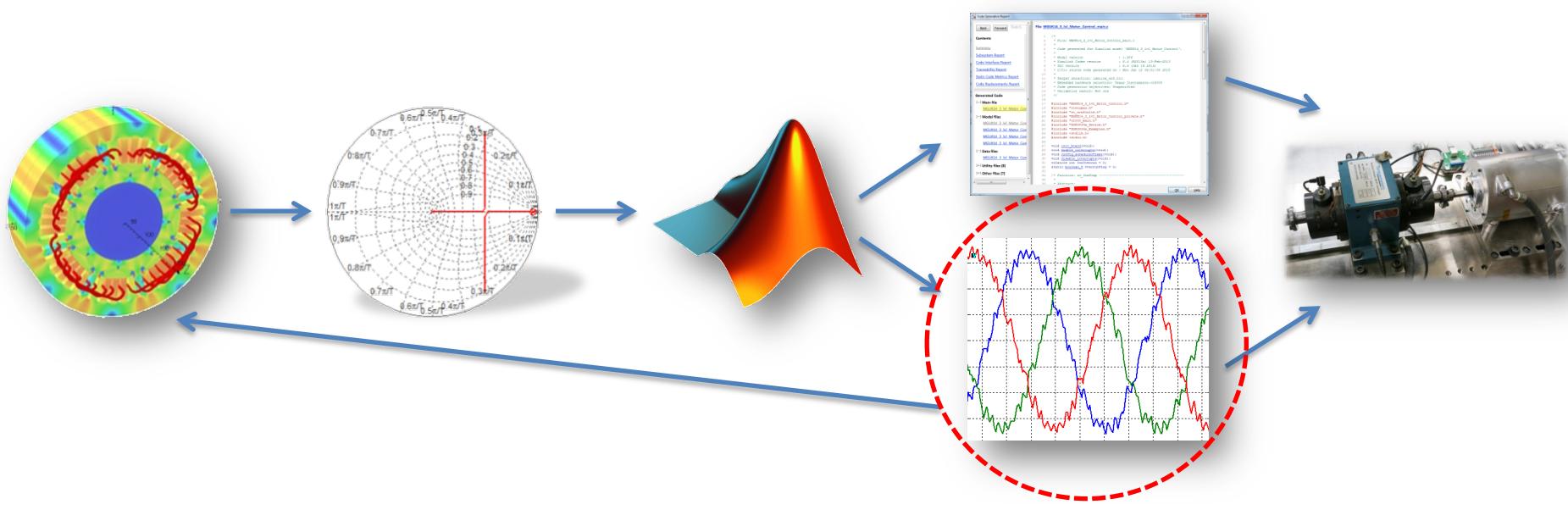
Simulation

- Parameters imported from motor control design
- Quick view of simulation results
- Custom motor control library
 - Design blocks
 - Easy to implement different control topologies
- Verify motor control
 - Gains from control design
 - Different control topologies
- Data can be saved for further analysis



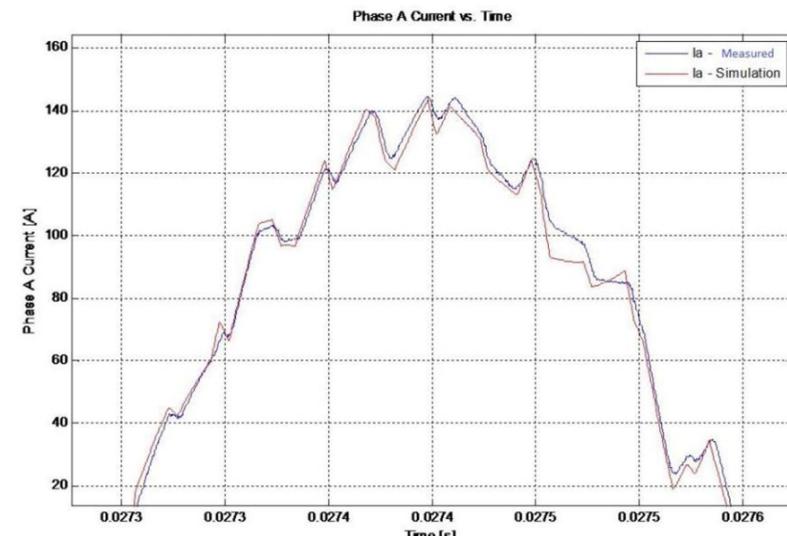
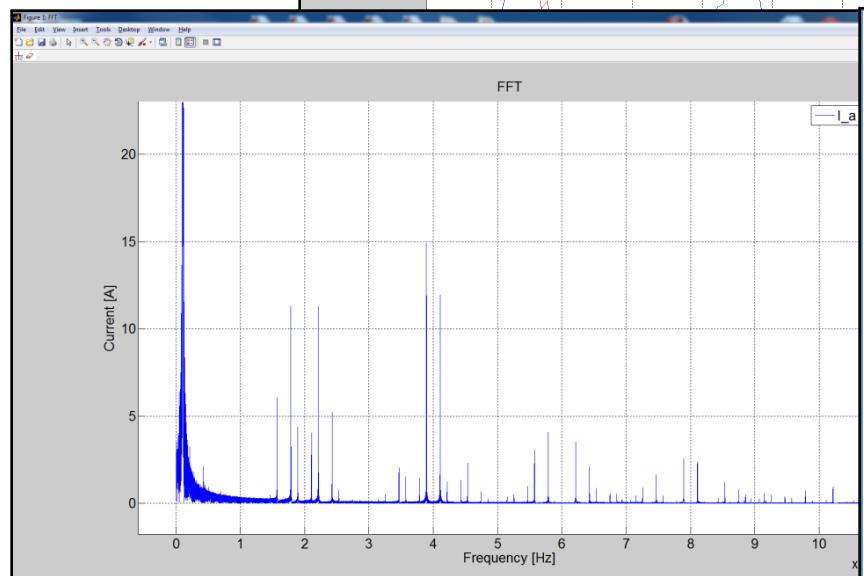
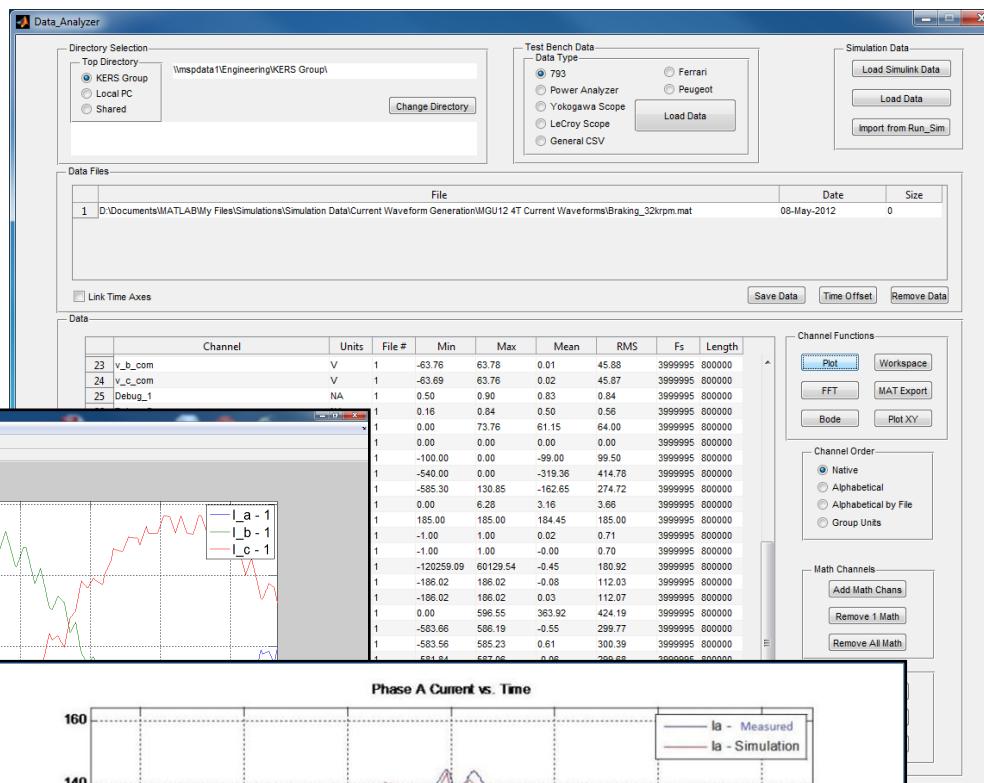
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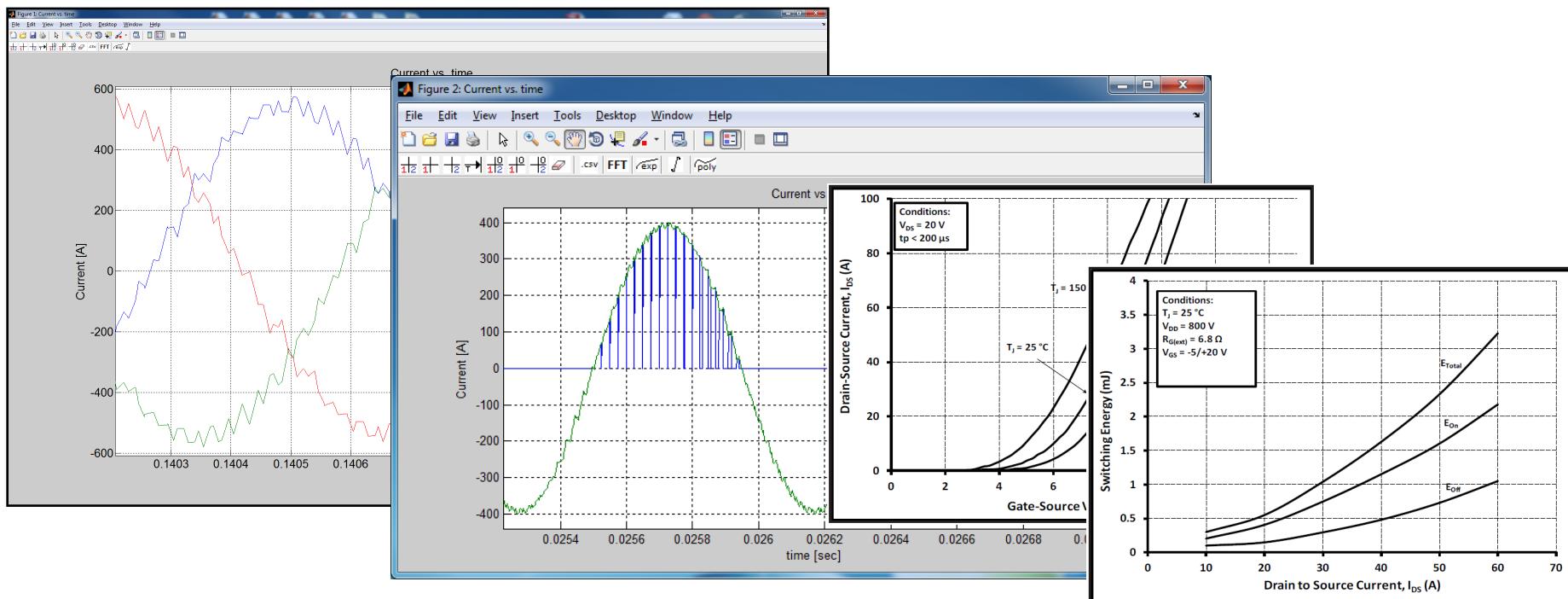
Data Analysis

- Import simulation and experimental data
- Compare data
- Functions to analyze data



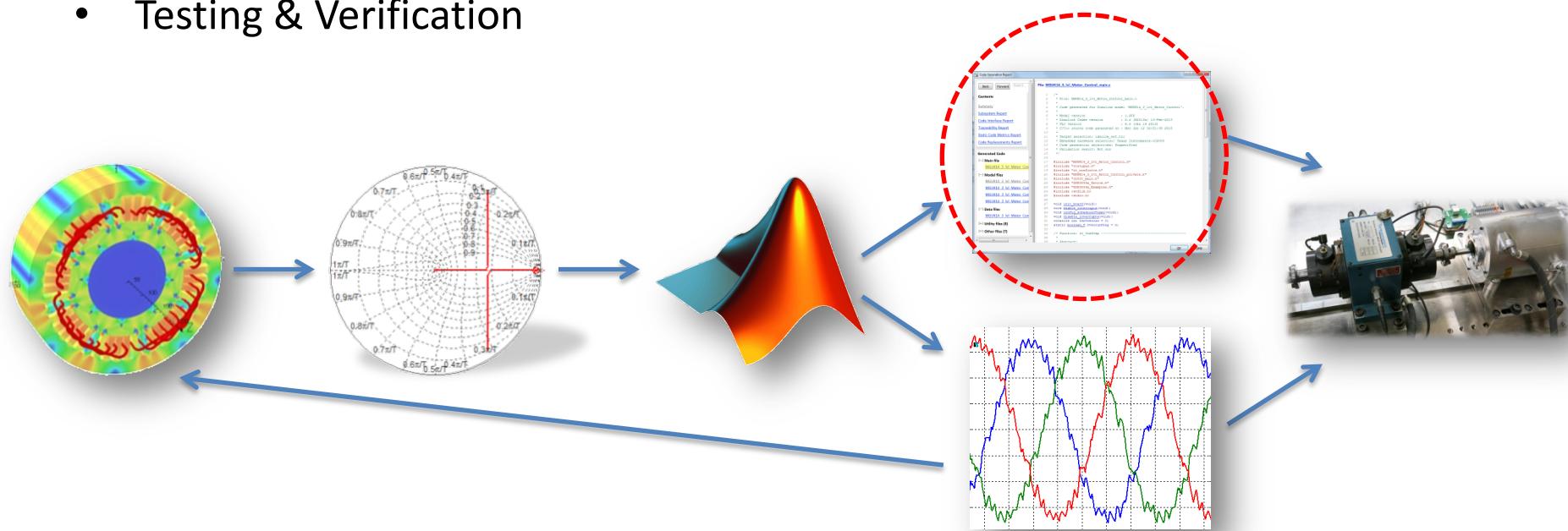
Hardware Design

- Phase currents fed back into FEA to estimate motor losses
- Device currents used to calculate power electronics losses and heating
- DC RMS current and voltage ripple used for capacitor sizing
- RMS currents used for bus bar sizing



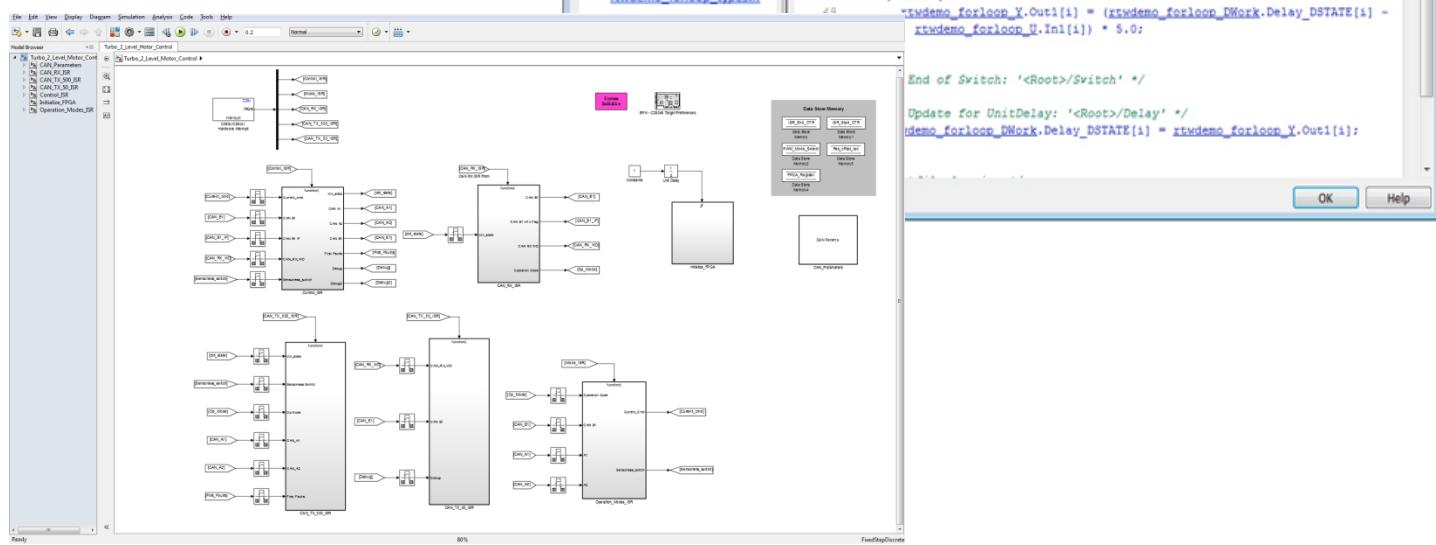
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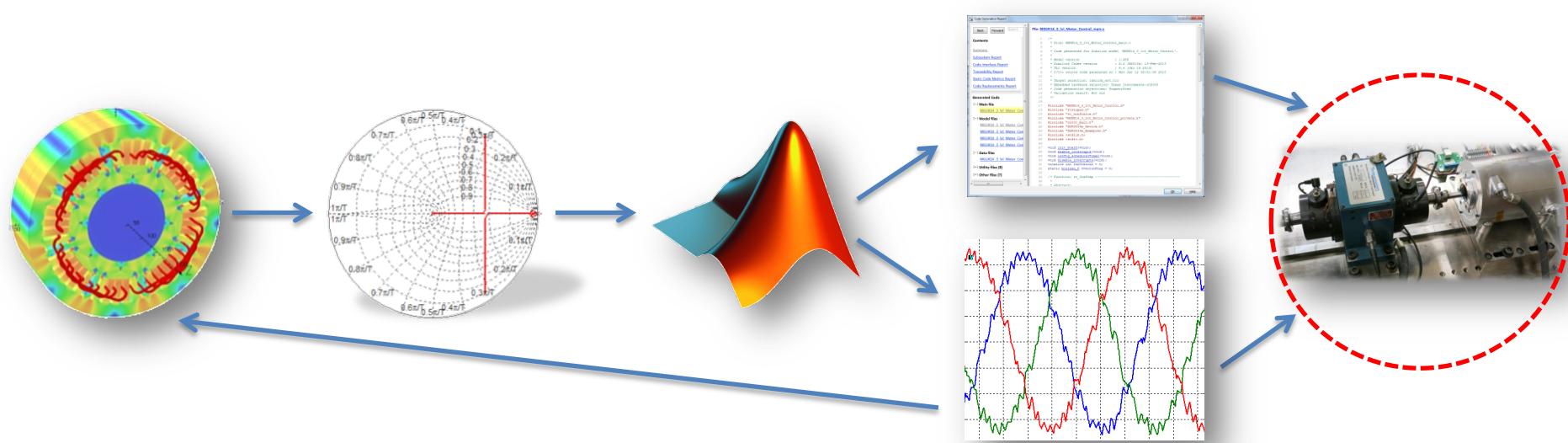
Code Generation

- Simulink Coder builds DSP/FPGA code directly from Simulink blocks
- Develop and verify code with simulation
- Deploy exact code in hardware
- Allows for rapid prototyping



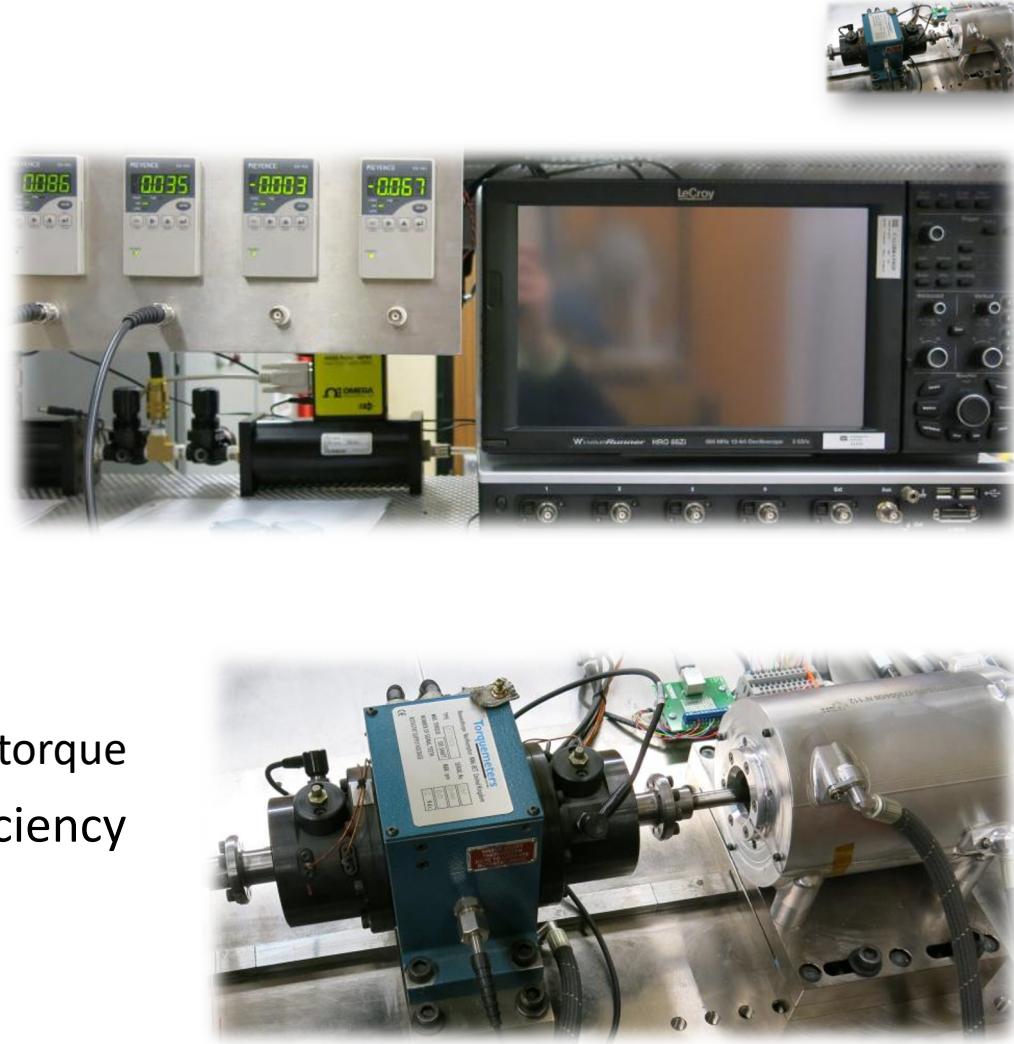
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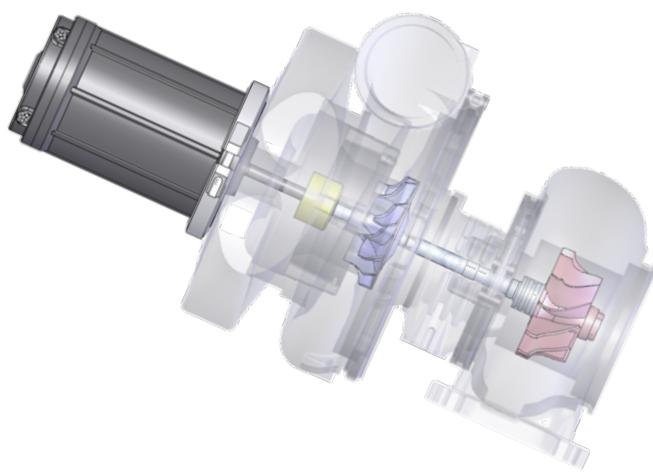


Testing & Verification

- Calibrate drive
- Verify back-emf
- Bearings break-in
- Verify control
 - DQ current regulators
 - Field weakening, I_d , I_q
 - Torque accuracy
 - Tune sensorless control
 - Run motor to full speed and torque
- Measure motor and drive efficiency



Applications ...



Questions Please ?



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